

Product Information

**New
Production**

3D vision system(HV-P series)

RPI-0175

Date of issue : 1st July 2020

■ Release overview

3D vision system 『HV-P series』 has been released in order to enable to construct machine vision system combined with Hirata robots. This product has 3D vision (camera), controller, and software.

By combining with Hirata robots, it can be realize an application such like random piled-picking etc.

■ Period of starting orders

July 2020

■ Main feature

Controller can easily set connection with external devices, adjusting shooting conditions, by touch panel operation. It has Parameter auto-adjusting function to set some important parameters in vision system such like a "camera exposure light time" and so on.


Using taken images, possible to do Off-line validation. And the validation result can be sent the controller, so that, it can support quick start-up of the system.

Main feature	Detail
4 types of 3D visions are lined-up	Selectable from 4 types of 3D visions (camera) according to your needed field of view to measure.
Project/Task management function	Multiple tasks can be registered, and it can be edit (add, set, delete and copy) . Tasks can be registered by each work-pieces, and it can be operate by switching. ※The "task" means a unit of work of system, such like "inspecting work-piece", "Picking & placing the work-piece". ※The task of inspection for some different work-pieces can be managed together as an unit called "Project".
Multi-color light projection function	7 (white, red, green, blue, cyan, magenta, yellow) colors of light projection is possible. Selectable proper color according to surface characteristics of work-pieces.
Connection with robot, Calibration function	Standard support for connection function with Hirata robot/controller (HNC). Possible to connect in standard setting.
Operation function (Add, set, delete, copy)	For each operation, dedicated setting display is prepared, it can be edited easily. ※The "Operation" means an unit of motion which cannot be indecomposable anymore in Task, such like "3D matching(recognizing work-piece)", "3D picking (calculating position to grip by robot)".
User own operation adding function	Possible to add operations created on User's own accord.
Utility function of communication	Utility function, like status check of communication with external devices, or Testing


check and log etc.	by image logs, is prepared.
Touch operation	With touch operation, zooming, moving and setting change is available.
Multi-language	Standard language is Japanese and English. Regarding the other languages, please contact us.

■ Model

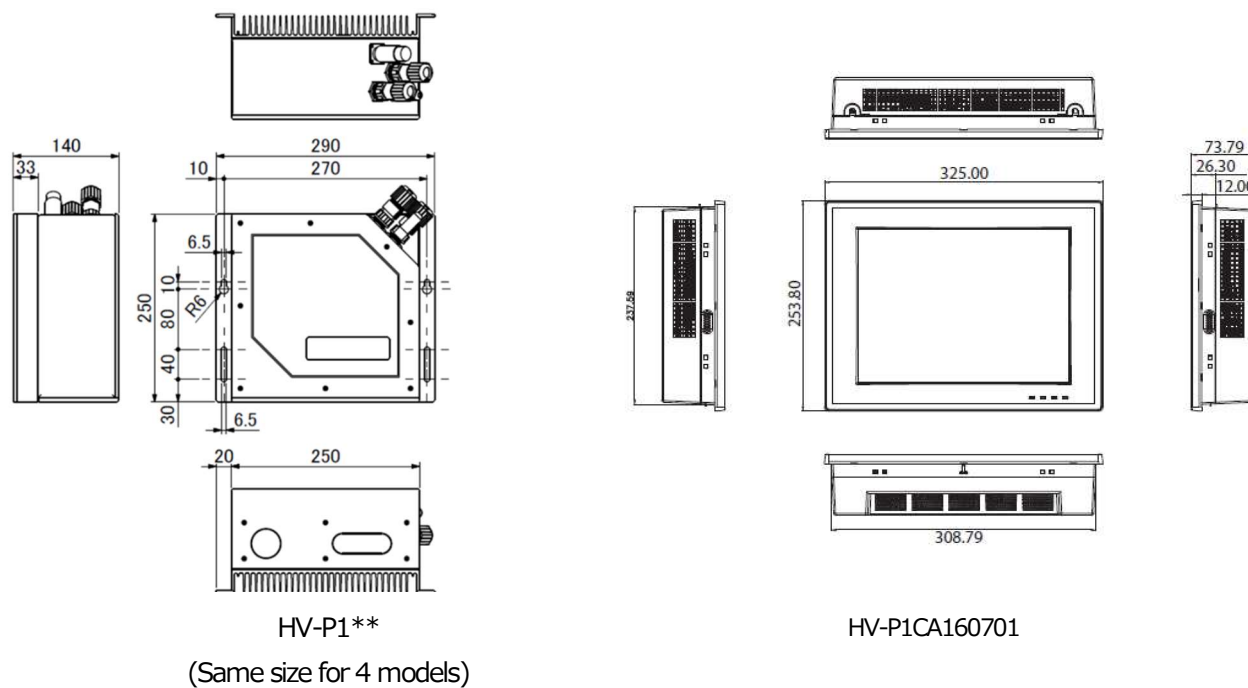
3D vision is prepared 4 types depends on a distance between the shooting target (hereinafter called WD).

Model	HV-P103	HV-P106	HV-P110	HV-P115
WD	250 - 300 mm	500 - 600 mm	800 - 1000 mm	1200 - 1500 mm
Field of view	115x180 mm	225x340 mm	360x515 mm	540x750 mm
External dimension	290 x 250 x 140mm			
				
Weight	6.5 kg			
Power supply	DC24V±10%			
Power source	Rated 7.1A			
Protection level from water/dust	Approx. IP64			
Environmental temperature during operation	0 - 45°C			
Max number of camera connections	2 cameras (1 camera is external)			
Measurement method	Pattern projection			
Communication method	1000BASE-T (IEEE 802.3z)			
Shooting trigger	Software trigger/ hardware trigger			
Resolution (per 1px)	0.15x0.2 mm	0.25x0.3 mm	0.45x0.5 mm	0.55x0.6 mm

Controller is common for all 3D visions.

Model	HV-P1CA160701
Appearance	
Power supply	DC 12-30V (65W)
Environmental temperature during operation	0~50°C
Storage temperature	-40 ~ 60°C
Humidity	10~95% @40°C (※No condensation)
Protection level from water/dust	Approx.IP64 (※Only front panel)
Weight	3.8kg
External dimension	325 x 253.8 x 73.8 mm
Language	Japanese / English

■ External view



■ Screen image

